



K2 (6)

School of Basic Sciences

Bachelor of Science Honours in Mathematics Summer Term Examination – July - August 2024

Duration : 180 Minutes Max Marks : 100

Sem IV - C1UC401B - Computational Mathematics

<u>General Instructions</u> Answer to the specific question asked Draw neat, labelled diagrams wherever necessary Approved data hand books are allowed subject to verification by the Invigilator

1)	Write the integral of $x^2 e^{-4x}$.	K1 (3)
2)	Define if else loop and print even or odd integers from given data set.	K2 (4)

- 3) Define
 - 1. Eigenvalues and Eigenvectors command in SageMath.
 - 2. Inner Product Space command in SageMath
- 4) Find the general solution of the following first order ODE: dy /dt y = $^{K3}(6)$ e^(2t).
- Create Sage code that will calculate the number of primes less than K3 (6) 2015.
- 6) By using for loop, find a list of all the numbers between 1 and 1000 K3 (9) that are multiples of 3 and 5.
- ⁷⁾ Find the singular value decomposition of a matrix A=[1 -4;3 4]. K^{3 (9)}
- ⁸⁾ Write sagemath code by using Taylor series method to determine K4 (8) value of y corresponding to x=2, given that $\frac{dy}{dx} = x + 2y$ and y(1) = 1.
- 9) Write a sagemath code to calculate the root of a equation f(x) = 0 by K4 (12) iterative method.
- ¹⁰⁾ Calculate the largest Eigen value and corresponding Eigen vector of $K^{5}(10)$ the matrix $\begin{bmatrix} 5 & 4 \\ 2 & 2 \end{bmatrix}$ by the power methods.
- Write a sagemath code to calculate f(5) by Newton's divided K5 (15) difference interpolation formula for given data set for the given set of points (9, 2), (3, 10), (1,15).

Write a sagemath code to calculate f(5) by Lagrange interpolation ^{K5 (15)} formula for given data set for the given set of points (9, 2), (3, 10)

¹²⁾ Use Gram-Schmidt to determine orthonormal basis of the basis $\{(1, 1, 0), (1, 0, 1), (0, 1, 1)\}$.

OR

Apply the Gram-Schmidt orthogonalization process estimate an ^{K6 (12)} orthogonal basis from a basis

{(2; -1; 3; 1); (3; 3; 4; 0); (1;-2; 0;-1); (4; 5; 5;-1)}.