

School of Engineering
B.TECH Mechanical Engineering
Semester End Examination - Nov 2023

Duration : 180 Minutes
Max Marks : 100

Sem VII - BME072 - Automatic Control Systems

General Instructions

Answer to the specific question asked

Draw neat, labelled diagrams wherever necessary

Approved data hand books are allowed subject to verification by the Invigilator

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| 1) | Explain the concept of performance indices in control systems. What role do they play in evaluating control system performance? | K1 (2) |
| 2) | How does the analog-to-digital converter impact the accuracy and performance of a digital control system? | K2 (4) |
| 3) | Apply the Popov's stability criterion to analyze the stability of a non-linear system with appropriate constraints. | K2 (6) |
| 4) | How does the design process of a digital control system using state feedback differ from classical state feedback in continuous-time control? | K3 (9) |
| 5) | Describe the steps involved in using the z-transform for analyzing the transient response of a digital control system. Provide an example. | K3 (9) |
| 6) | Compare the stability analysis results obtained using the bilinear transform and the Jury method. Under what conditions would one method be preferred over the other? | K5 (10) |
| 7) | Create a stability analysis framework that combines Liapunov's stability criterion and Popov's stability criterion for a complex non-linear system. | K4 (12) |
| 8) | Design a comprehensive control strategy for a challenging non-linear system by integrating Liapunov-based stability analysis, describing function method, and phase plane analysis. | K5 (15) |
| 9) | Develop a computational tool or software that automates the stability analysis and design process for non-linear control systems, incorporating multiple stability criteria. | K5 (15) |
| 10) | Find the inverse Laplace transform of $F1(s) = \left(\frac{1}{s+2}\right)^2$ | K6 (18) |